Python Level 1 with Virtual Robotics Mission 9 Objective 5 Line Sensor Readings Name:

Use this document to chart the line sensor readings while driving on the black line.

- Open the console and then run the code.
- Stop the program execution after a few seconds.
- Record the sensor readings.
- Change the readings from Boolean to Binary.
- Highlight each unique reading and cross out repeat readings.
- Compare your chart to the one in the instructions.

First time it appears	Boolean Values	Binary Values
X	(False, True, True, False, False)	(0, 1, 1, 0, 0)

